

# An Incremental Model Selection Algorithm Based on Cross-Validation for Finding the Architecture of a Hidden Markov Model on Hand Gesture Data Sets

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# Hidden Markov Models

## Graphical network

- $N$  hidden states
- $M$  mixture components in these hidden states
- Connectivity between hidden states

# Hidden Markov Models

## Probability model

- Initial state probabilities
- Observation probabilities
- State transition probabilities
- Baum-Welch algorithm using Expectation-Maximization

# Hidden Markov Models

Models used in this paper

- Left-right model
- Left-right-loop model
- Full model

# Hidden Markov Models

- Bioinformatics (Secondary structure prediction)
- Speech processing (Audio modelling)

# Model Selection

## Bias-variance tradeoff

- Error = Bias + Variance
- Small/simple model underfits (bias high, variance low)
- Large/complex model overfits (bias low, variance high)

# Model Selection in HMM

- Hard to estimate number of hidden states & models in each state
- Need a methodology to optimize the model structure for novice user



# Structure Learning

## State Space Search

- Huge search space: All the combinations of number of hidden states and number of mixtures at each hidden state.
- Infeasible to try and evaluate all possible architectures
- Heuristic strategy visiting as few as possible states in the search space

# Structure Learning

## Operators

- Define operators. Example: ADD-1 from state  $HMM_{4,1}$  to  $HMM_{5,1}$
- Add operators for *forward search*
- Remove operators for *backward search*
- *Floating search* uses both

# Structure Learning

## Evaluation

- Compare performance metric of next state with current state
- Accept or reject operator based on improvement
- Takes into account both generalization error and complexity

# Structure Learning

## Dimensions of Search

- Initial state ( $HMM_{1,1}$  or  $HMM_{N,1}$ )
- State transition operators (Add or remove)
- Search beam (Single or multiple operator)
- State evaluation function (AIC, BIC, or CV)
- Termination condition (No improvement or fixed number of iterations)

# MSUMO Operators

- REMOVE-1: Remove a single hidden state from the HMM.
- ADD-1: Add a single hidden state to the HMM.
- REMOVE-L: Add a new Gaussian to the mixture.
- ADD-L: Remove a Gaussian from the mixture.

# MSUMO Pseudocode

```
1  BEST = initial network
2  while BEST changed
3    for each applicable operator OPERi
4      Ci ← OPERi(BEST)
5    Sort candidates Ci in the order of complexity
6    for i = 1 to number of candidates
7      Train and validate Ci on k folds
8      if Ci is more complex than BEST
9        Test H0 :  $\mu_{\text{BEST}} \leq \mu_{C_i}$ 
10       if H0 is rejected
11         BEST ← Ci
12       break
13     else
14       Test H0 :  $\mu_{C_i} \leq \mu_{\text{BEST}}$ 
15       if H0 is accepted
16         BEST ← Ci
17       break
18 return BEST;
```

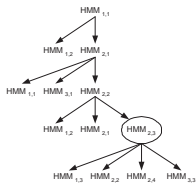
# Five MSUMO Variants



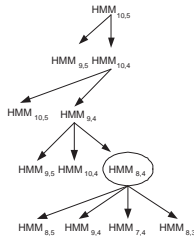
1-Fw



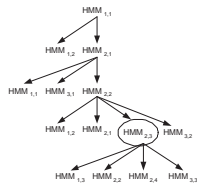
1-Bw



Fw



Bw



MFw

# Experimental Factors

- MSUMO variant used in search (1-Fw, 1-Bw, Fw, Bw, and MFw)
- Statistical test used in comparison ( $k$ -fold paired  $t$  test)
- Confidence level ( $1 - \alpha$ ) of the test (0.95)
- Correction used when applying multiple tests (Holm correction)



# HMM Training

- HMM toolbox implemented by Kevin Murphy
- Retraining of the architecture when an operator is applied
- No probabilities are kept or frozen

# Sign Language Datasets

Table: Properties of data sets.

	size	signs	features
IDIAP	490	7	20
eNTERFACE'06	760	19	32
British	980	91	22
Australian	6650	95	8

# Optimal Architecture

- Exhaustive search over 50 architectures
- Hidden states from 1 to 10
- Gaussian mixtures with 1 to 5 components

# Comparison Criteria

- The accuracy of the estimated architecture
- The complexity of the estimated architecture
- Computational complexity of the search until an architecture is found

## Two measures used in comparisons

**Table:** An example for calculation of ranks.

	Fw	Bw	MFw	1-Fw	1-Bw
Order	3	2	1	1	2
# states	10	5	3	4	5
Rank	5	3.5	1	2	3.5

- *Order*: Has the optimal architecture in position one, second best architecture in position two, and the worst architecture in the last position
- *Rank*: Takes also into account how fast we get to the final state, which uses the number of states visited as a measure of the complexity of search

# Comparison of MSUMO variants using no statistical test

Average	MFW	1-Fw	1-Bw	Fw	Bw	Best
Rank	2.8	3.9	4.2	2.6	1.6	
Order	9	37	36	8	5	
# states	14	4	2	12	5	
Error	28.18	36.71	34.28	28.48	28.00	27.17

# Comparison of MSUMO variants using $k$ -fold paired $t$ test with no correction

Average	MFW	1-Fw	1-Bw	Fw	Bw	Best
Rank	3.2	2.9	3.6	2.9	2.3	
Order	26	35	29	25	9	
# states	5	2	7	4	15	
Error	35.57	39.67	34.94	35.26	29.57	28.27

# Comparison of MSUMO variants using $k$ -fold paired $t$ test with Holm correction

Average	MFw	1-Fw	1-Bw	Fw	Bw	Best
Rank	3.0	2.5	3.8	2.7	3.0	
Order	18	26	24	17	10	
# states	5	2	7	4	15	
Error	36.28	39.67	34.94	35.28	29.6	31.00



# Summary

- Proposed the MSUMO algorithm for model selection in HMM
- Five variants including forward/backward search with single and multiple operands
- Compared architectures w.r.t. expected error, complexity and distance to the optimal algorithm

# Conclusions

- Conservativity of the selection criteria increases, the algorithm tends to find simpler models.
- If only error is important, we should use MSUMO with no statistical tests.
- BW finds the most accurate architectures, but with an increased number of visited states compared to other algorithms.

## Future Work

- Architectures where states contain different gaussian mixtures
- Jumps with multiple steps (Heuristics)

# Questions?